# Multiple forces can be applied to an object (for AP Physics 1 and 2)

## First principles

A **force** is a push or a pull exerted on an object by another object.

$$[F] = N$$

#### **Newton I**

The sum of all external forces acting on a material object equals zero only for all times when the object's velocity is staying constant.

$$\sum \vec{\mathbf{F}} = \vec{\mathbf{0}} \Leftrightarrow \text{constant } \vec{\mathbf{v}}$$

#### **Newton II**

The velocity of a material object changes at a rate proportional to the sum of all external forces on the object and inversely proportional to the object's inertial mass.

$$[m_{\mathrm{I}}] = \mathrm{kg}$$
 $\vec{\mathbf{a}} = \frac{\sum \vec{\mathbf{F}}}{m_{\mathrm{I}}}$ 

#### **Newton III**

Each force has a partner force of equal magnitude and opposite direction, with the roles of the object doing the pushing and the object being pushed exchanged.

There exists 
$$\vec{\mathbf{F}}_{\_,2\rightarrow1}$$
 $\Rightarrow$ 

there also exists

 $\vec{\mathbf{F}}_{\_,1\rightarrow2} = -\vec{\mathbf{F}}_{\_,2\rightarrow1}$ 

### **Common forces**

Origin	Force	Label	Magnitude formula	<b>Direction</b> relative to object being acted on
Peripheral proximity to Earth	<b>Gravitational</b> (Newtonian)	$F_{ m G}$	$m_{\mathbb{G}}g$	From object toward Earth
Proximity to massive object			$rac{\mathit{Gm}_{\mathbb{G},1}\mathit{m}_{\mathit{G},2}}{\mathit{r}^2}$	From object to other mass
Contact with stretched string	Tension	Т	No memorized formula	From object back into string
Contact with surface	Normal	N	No memorized formula	⊥ to contact plane, pushes back into object
	Static <b>friction</b>	<i>f</i> s	Less than greatest sustainable (for a given $N$ ) $f_{\rm S} < \mu_{\rm S} N$ Greatest sustainable ("") $f_{\rm S} = \mu_{\rm S} N$ Unsustainable ("") $f_{\rm S} > \mu_{\rm S} N$	∥ to contact plane, opposes interfacial slippage
	Kinetic friction	$f_{\mathrm{K}}$	$\mu_{\rm K}N$	
Contact with spring	Spring (Hookean)	$F_{ m SPR}$	$k \Delta x $	Opposes spring deformation
Contact with fluid medium	Drag	$F_{ m DRAG}$	$\uparrow v_{\rm OBJ,FL} \Rightarrow \uparrow F_{\rm DRAG}$	Opposes motion of object through fluid
	Buoyant	$F_{ m BUOY}$	$ ho_{ ext{FLUID}} V_{ ext{REPL}} g$	Opposes weight
Proximity to other charge	Electric (Coulomb)	$F_{ m E}$	$\frac{k q_1  q_2 }{r^2}$	Opposites attract; like repel
			q E	$\vec{F}_{E} \parallel \vec{E}$ for (+) test charge
Proximity to			$ q v \sin\theta B$	
other moving charge(s)	<b>Magnetic</b> (Lorentz)	$F_{ m B}$	$I\ell \sin\theta B$	RHR

There is **no such force as "the net" force**. The phrase "the net force" refers to the sum of all *actual* forces acting on a system.

## **Problem-solving algorithm**

- 1. Carefully **read** problem three times.
- 2. **Sketch system(s)** of interest enclosed in dashed bubble(s) and sketch relevant aspects of the environment.
- 3. List any **givens** not already sketched. List requested **unknowns**.
- 4. For each system of interest, draw a dot diagram with signed Cartesian axes.
  - Include all actual forces. Ask the following questions and obtain, as needed, *labels* from the table of common forces.
    - i. Is the **Earth nearby?**
    - ii. Is anything touching the system?
    - iii. Other than the Earth, are any massive objects nearby?
    - iv. Any charges nearby?
    - v. Any moving charges nearby?
  - b. Do not include extraneous forces. All forces on a dot diagram must act **on** the object represented by the dot.
  - c. Populate a spreadsheet of force components (e.g.  $F_x$  and  $F_y$ )
  - d. If dot diagrams for multiple systems are drawn, recognize each interaction force pair (equal magnitudes).
  - e. **Sum up forces** in each column of spreadsheet  $(\sum F_x = ma_x \text{ etc.})$
- Solve resulting system of equations for unknowns (or determine unknowns directly in cells of spreadsheet).
   Sometimes, substituting formulas for magnitudes might be necessary.
- 6. Remember: **Base your reasoning on Newtonian principles**, not on "what it feels should be the case."